



**WIPER MECHANISMS**

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# OSLV.com

Research  
Technology  
High Quality



La divisione della OSLV Italia dedicata alla produzione di impianti per tergitricristalli, realizza motoriduttori tergi, cinematismi, cinematismi compatti, bracci e spazzole tergi che vengono impiegati su mezzi agricoli o per movimentazione terra, veicoli militari, autobus, treni, mezzi elevatori e automobili come Lamborghini e McLaren. Attraverso un attento studio delle esigenze dei singoli clienti ed una stretta collaborazione con lo staff tecnico, è possibile progettare soluzioni personalizzate.

OSLV Italia's sector dedicated to the production of complete wiper systems, realizes wiper motors, wiper mechanism, wiper compact kinetics, wiper arms and blades that are used and mounted on different means such as agricultural and earthmoving machines, industrial and military vehicles, trains, busses, forklifts and cars such as Lamborghini and McLaren.

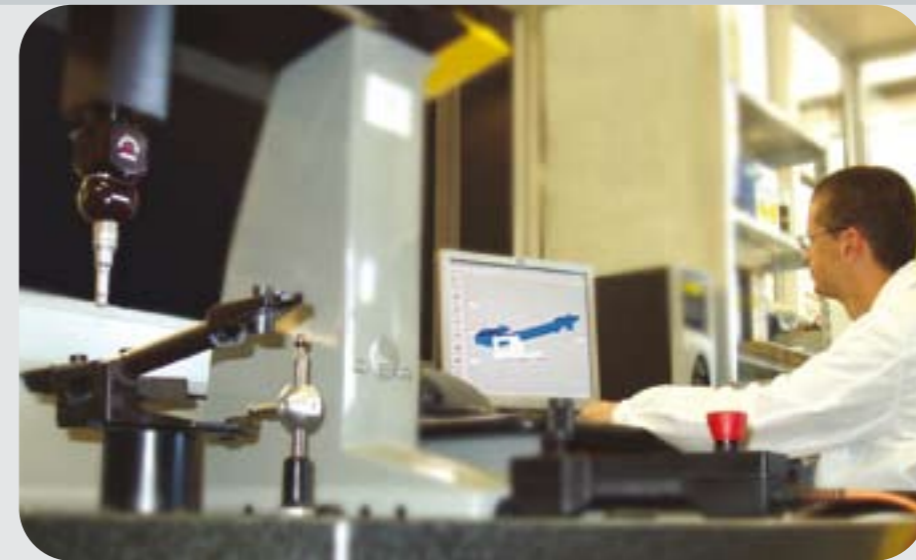
Through a careful analysis of each single inquiry and with the interaction between the customer and our technical staff, it is possible to develop customized solutions.

Le secteur de OSLV Italia qui se occupe de la fabrication de ensembles d'essuie glace, réalise moteurs essuie glace, tringleries, bras et balais essuie glace qui sont employées sur des moyens comme les véhicules agricoles et de terrassement, véhicules militaires, trains, autobus, élévateurs et automobiles comme Lamborghini et McLaren.

Par une étude soignée des exigences de chaque client, le personnel technique avec l'interaction du client même, réussit à concevoir des solutions innovantes et personnalisées.

In der Wischersysteme Abteilung von OSLV Italia, werden Wischermotoren, kompakte Kinematik, Wischerarme und Wischerblätter hergestellt, die in den unterschiedlichsten Mitteln eingebaut werden, sowie in Landwirtschaftsmaschinen, Erdbewegungsmitteln, Militärkraftfahrzeuge, Züge, Autobus, Gabelstapler und Autos wie Lamborghini und McLaren.

Auf der Grundlage eingehender Studien der Bedürfnisse jedes einzelnen Kunden und in Zusammenarbeit mit dem Team des technischen Büros, werden innovative und kundenspezifische Lösungen ausgearbeitet.



SINCERT



La OSLV Italia ha due distinti settori produttivi:

- **IL SETTORE AUTOMAZIONE** - è specializzato nella produzione di motori e motoriduttori a corrente continua e di attuatori elettrici.
- **IL SETTORE TERGENZA** - si occupa di progettare e realizzare completi sistemi di tergitricristalli per veicoli.

La peculiarità della nostra azienda è nella grande flessibilità produttiva, che ci permette di personalizzare i prodotti con le specifiche dei clienti, spondo al meglio le loro esigenze anche in termini di consegna.

OSLV Italia has two different production lines:

- **The Automation Sector** - which is specialized in the production of DC motors and gearmotors as well as electrical actuators.
- **The Wiper Sector** - which develops and produces complete wipersystems for vehicles.

The company distinguishes itself for the flexibility in manufacturing that enables it to customize products respecting customers' requests also in view of the lead time.

OSLV Italia a deux lignes de production différentes:

- **Le Secteur Automatisation** - il est spécialisée dans la production des moteurs et motoréducteurs en courant continue e des vérins électriques.
- **Le Secteur d'Essuyage** - il s'occupe de la réalisation des ensembles d'essuieglace complets pour véhicules.

La force de notre entreprise est la flexibilité productive que nous permet de personnaliser les produits selon les spécifications des clients en ligne avec leur exigences aussi en ce qui concerne les délais.

OSLV Italia hat zwei verschiedene Produktlinien:

- **Der Bereich Antriebstechnik** - ist in der Herstellung von Gleichstrom-Getriebemotoren und Motoren, sowie Spindelantriebe spezialisiert.
- **Der Bereich Wischersysteme** - entwickelt und produziert komplette Wischersysteme für Fahrzeuge.

Die Stärke unseres Unternehmens liegt in der großen Flexibilität in der Fertigung, die es uns ermöglicht, den Lieferzeiten gerecht zu werden.

## COMPACT SMALL (closed)

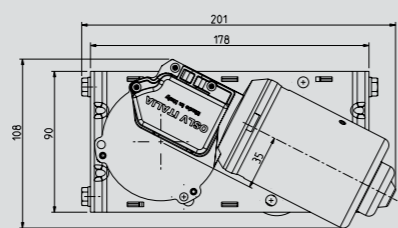
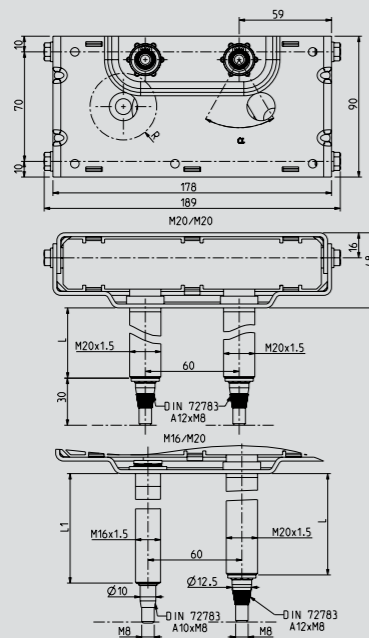


Dati tecnici / Technical Data

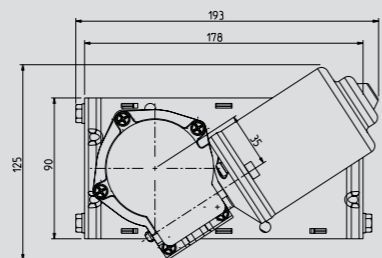
PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
Tensione nominale (V) Nominal tension (V)	12	24	12	24
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	1.5	2.5	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	40	40	40	40
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			50	

Cinematismo tergicristallo compatto per braccio pantografo e spazzola fino a 700 mm (chiuso)

Compact wiper mechanisms for pantograph arm and blades up to 700 mm (closed)



COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø62-35)



COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø62-35)

$\alpha$	45°	55°	60°	65°	70°	75°	80°	90°	105°
L (mm)	23	30	38	43,5	46,5	73	78	102	113
L1 (mm) = L + 5 mm									



## COMPACT SMALL (open)

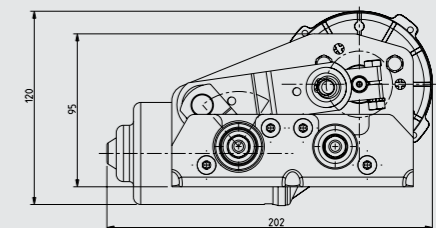
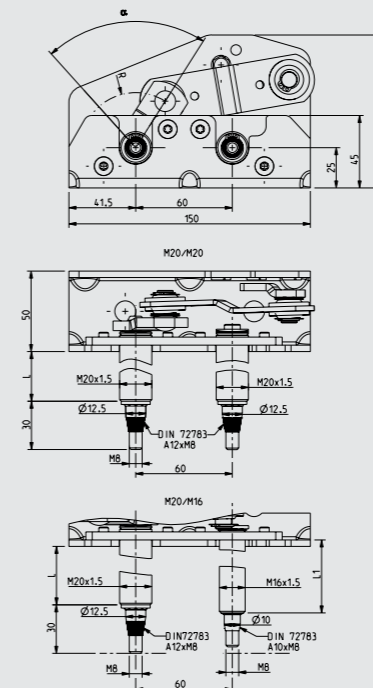


Dati tecnici / Technical Data

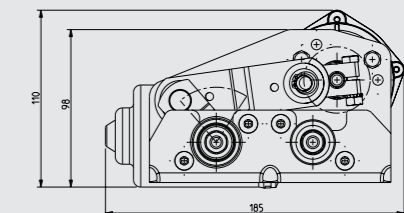
PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
Tensione nominale (V) Nominal tension (V)	12	24	12	24
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	2	2.5	2
Coppia nominale (Nm) Nominal torque	3	3	3	3
Coppia di spunto (Nm) Starting pair	30	30	45	45
Prima velocità (giri/min) First speed (rpm)	30		30	
Seconda velocità (giri/min) Second speed (rpm)			45	

Cinematismo tergicristallo compatto per braccio pantografo e spazzola fino a 700 mm (aperto)

Compact wiper mechanisms for pantograph arm and blades up to 700 mm (open)

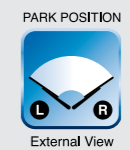


COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø62-43)



COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø62-43)

$\alpha$	45°	57°	60°	70°	72°	74°	75°	80°	82°	85°	90°	105°
L (mm)	30	54	55	55,5	58	60	61	80,5	102	-	-	-
L1 (mm) = L + 5 mm												



## COMPACT MEDIUM

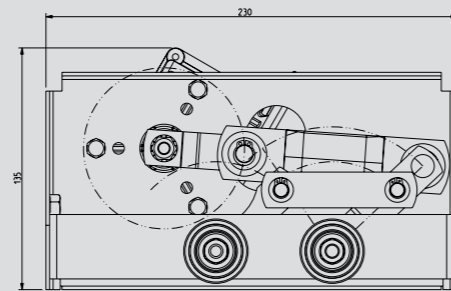
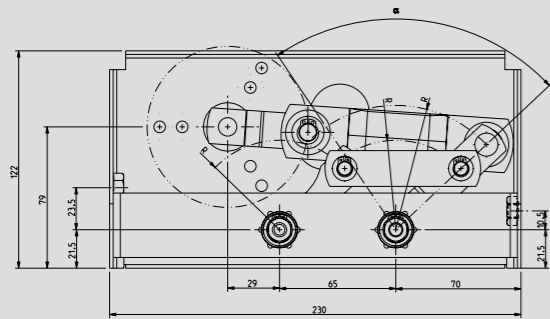


Dati tecnici / Technical Data

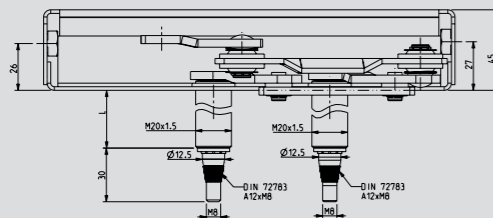
PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
Tensione nominale (V) Nominal tension (V)	12	24	12	24
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	1.5	2.5	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	40	40	40	40
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			50	

Cinematismo tergicristallo compatto per braccio pantografo e spazzola fino a 800 mm

Compact wiper mechanisms for pantograph arm and blade up to 800 mm



COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø76)



$\alpha$	50°	55°	60°	65°	80°	85°	90°
L (mm)	40	50	55	70	95	105	-



## COMPACT LARGE

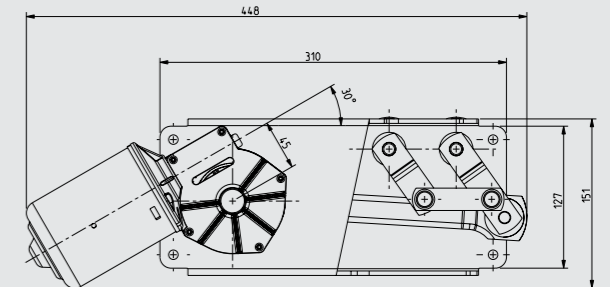
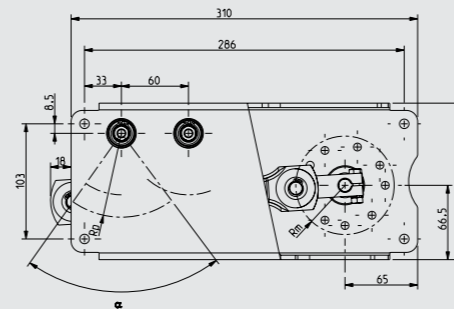


Dati tecnici / Technical Data

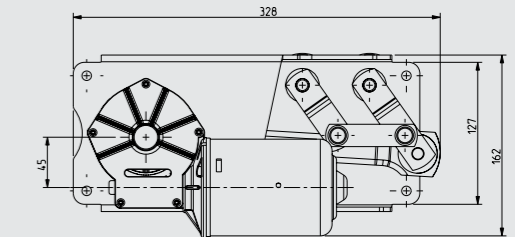
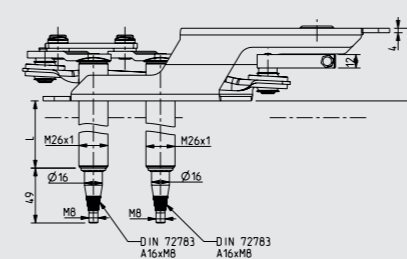
PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
Tensione nominale (V) Nominal tension (V)	12	24	12	24
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	3	2	3	2
Coppia nominale (Nm) Nominal torque	7	7	7	7
Coppia di spunto (Nm) Starting pair	55	65	55	65
Prima velocità (giri/min) First speed (rpm)	30		30	
Seconda velocità (giri/min) Second speed (rpm)			40	

Cinematismo tergicristallo compatto per braccio pantografo e spazzola oltre 800 mm

Compact wiper mechanisms for pantograph arm and blade up to 800 mm



COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø90)



COMPLETE WIPER MECHANISM (LINKAGE + DC GEARMOTOR Ø90)

L (mm)	82	102
$\alpha$	72°	72°



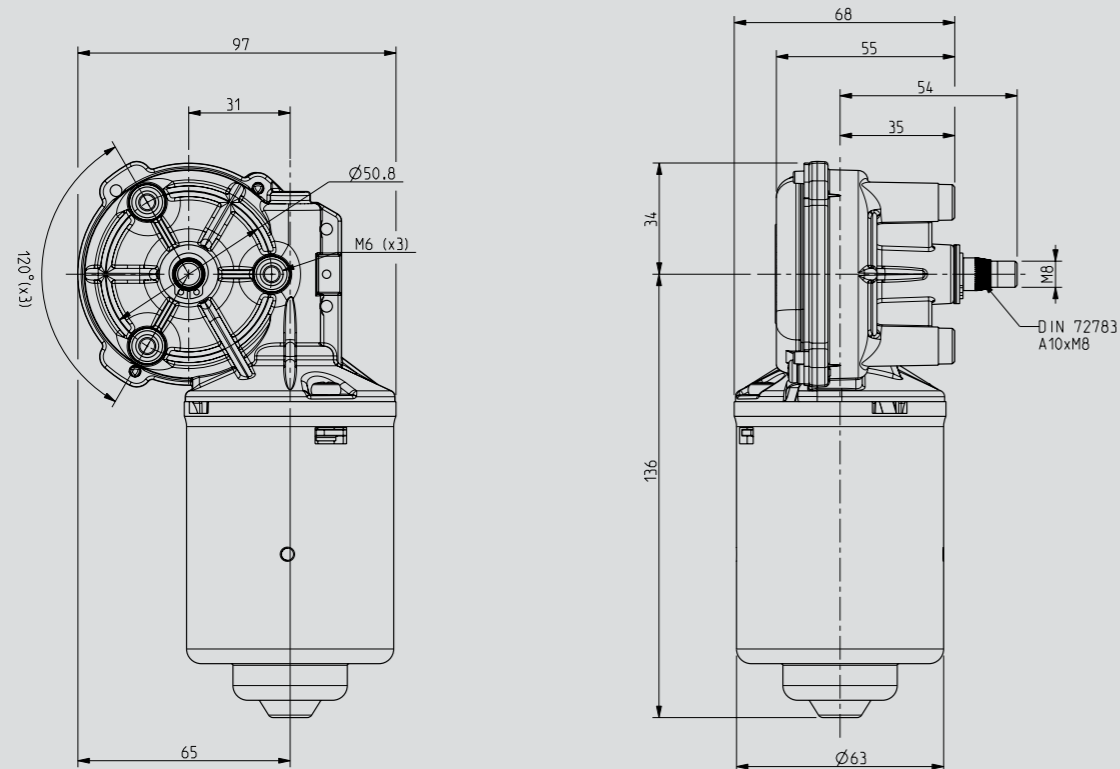
# MRT62-31

Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed.	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	1.5	1	2.5	2
Coppia nominale (Nm) Nominal torque	2.5	2.5	2.5	2.5
Coppia di spunto (Nm) Starting pair	25	25	25	25
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			45	



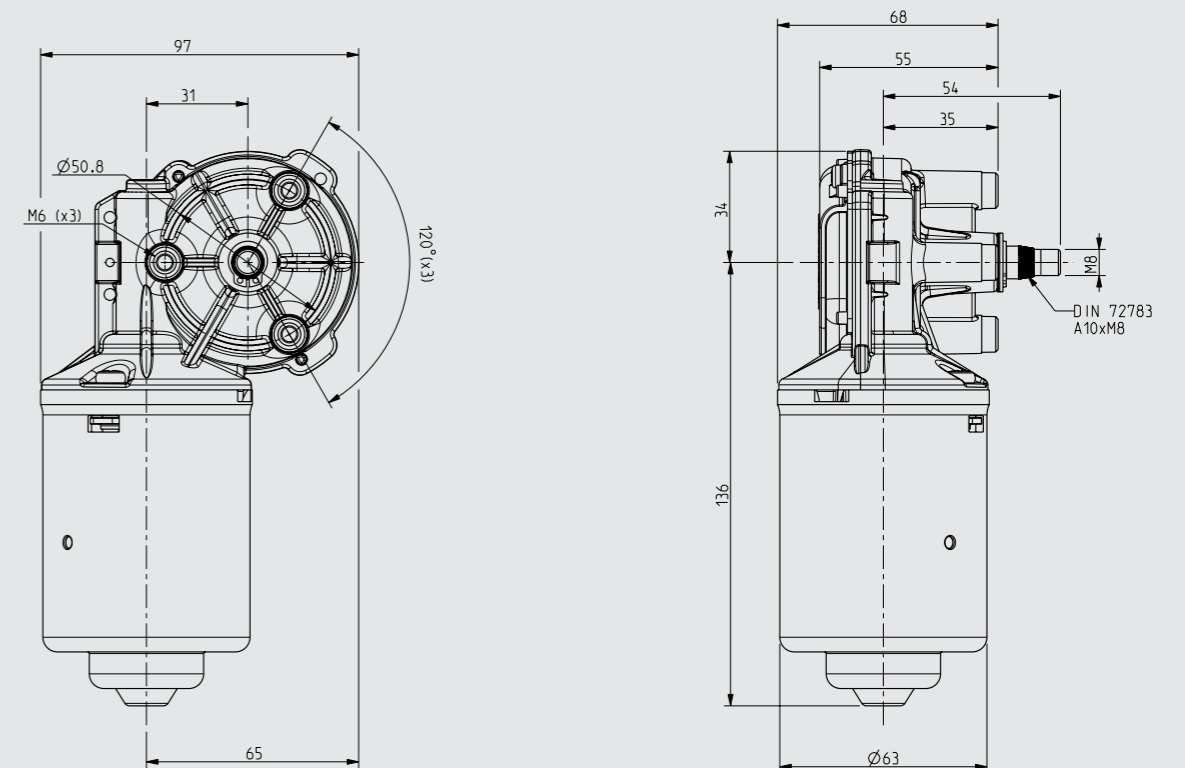
# MRT62-31

Destro / Right



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed.	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	1.5	1	2.5	2
Coppia nominale (Nm) Nominal torque	2.5	2.5	2.5	2.5
Coppia di spunto (Nm) Starting pair	25	25	25	25
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			45	



MRT62-31

MRT62-31

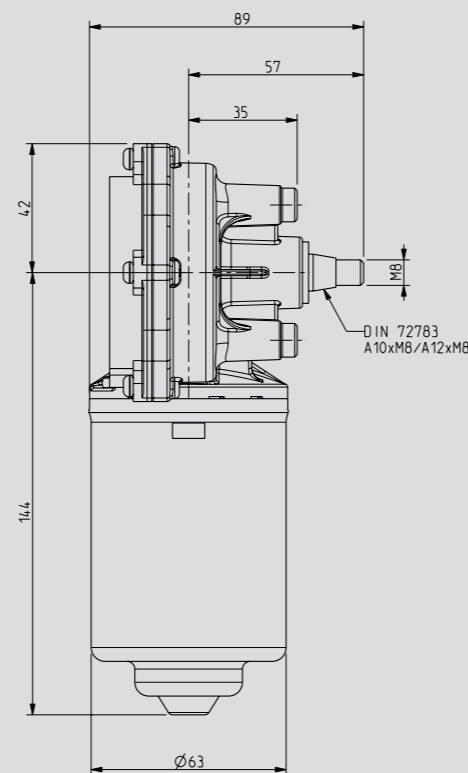
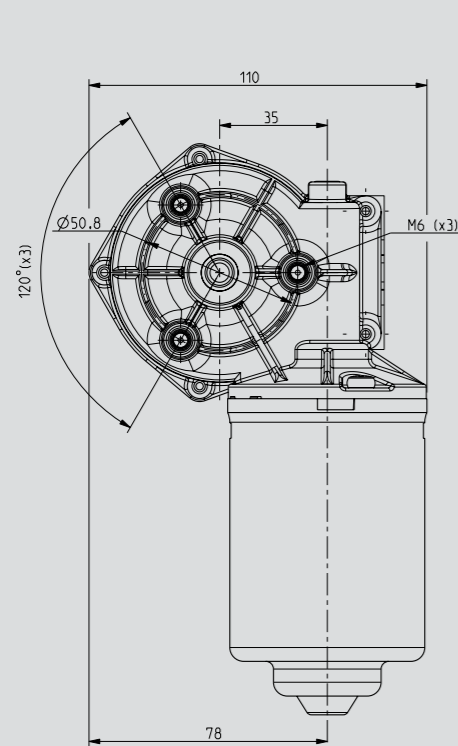
# MRT62-35

Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	2	2.5	2
Coppia nominale (Nm) Nominal torque	3	3	3	3
Coppia di spunto (Nm) Starting torque	30	30	45	45
Prima velocità (giri/min) First speed (rpm)	30		30	
Seconda velocità (giri/min) Second speed (rpm)			45	



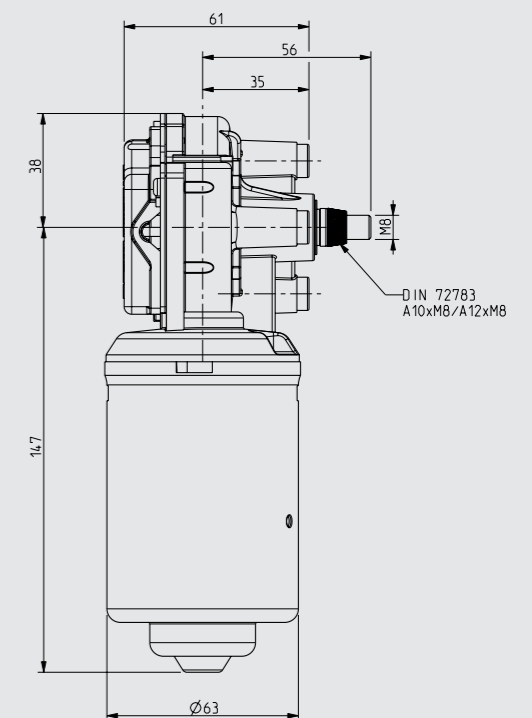
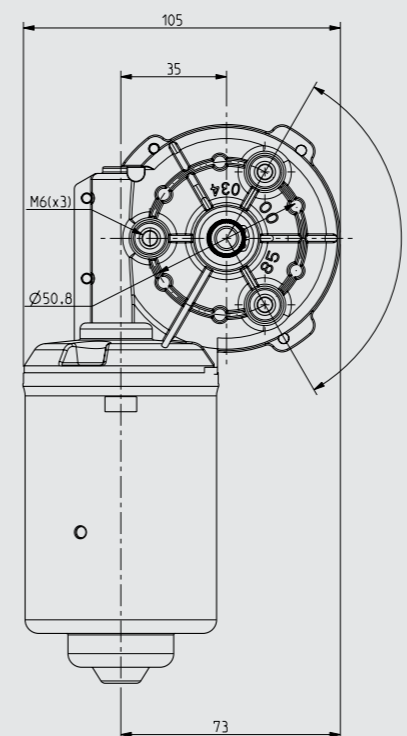
# MRT62-35

Destro / Right



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	2	2.5	2
Coppia nominale (Nm) Nominal torque	3	3	3	3
Coppia di spunto (Nm) Starting torque	30	30	45	45
Prima velocità (giri/min) First speed (rpm)	30		30	
Seconda velocità (giri/min) Second speed (rpm)			45	



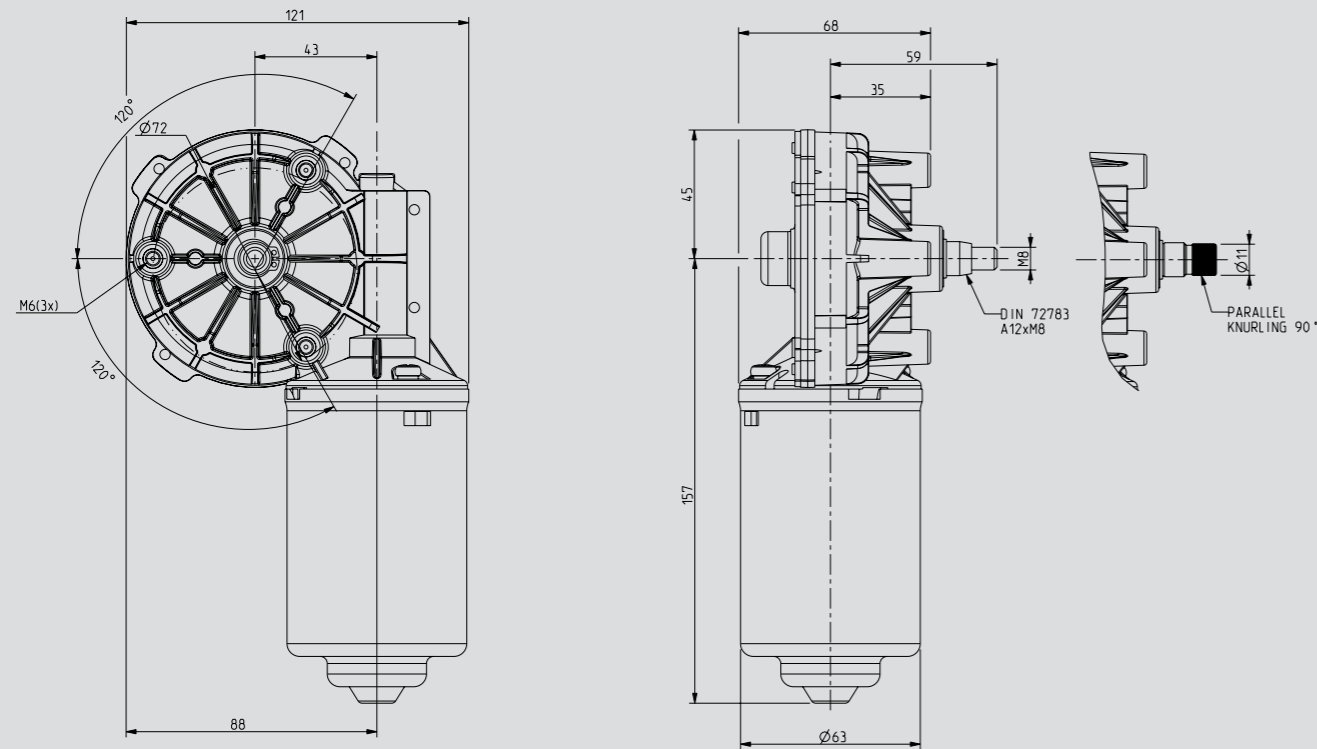
# MRT62-43 (Ø72)

Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2	1.5	2	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	40	40	45	45
Prima velocità (giri/min) First speed (rpm)	35		30	
Seconda velocità (giri/min) Second speed (rpm)			45	



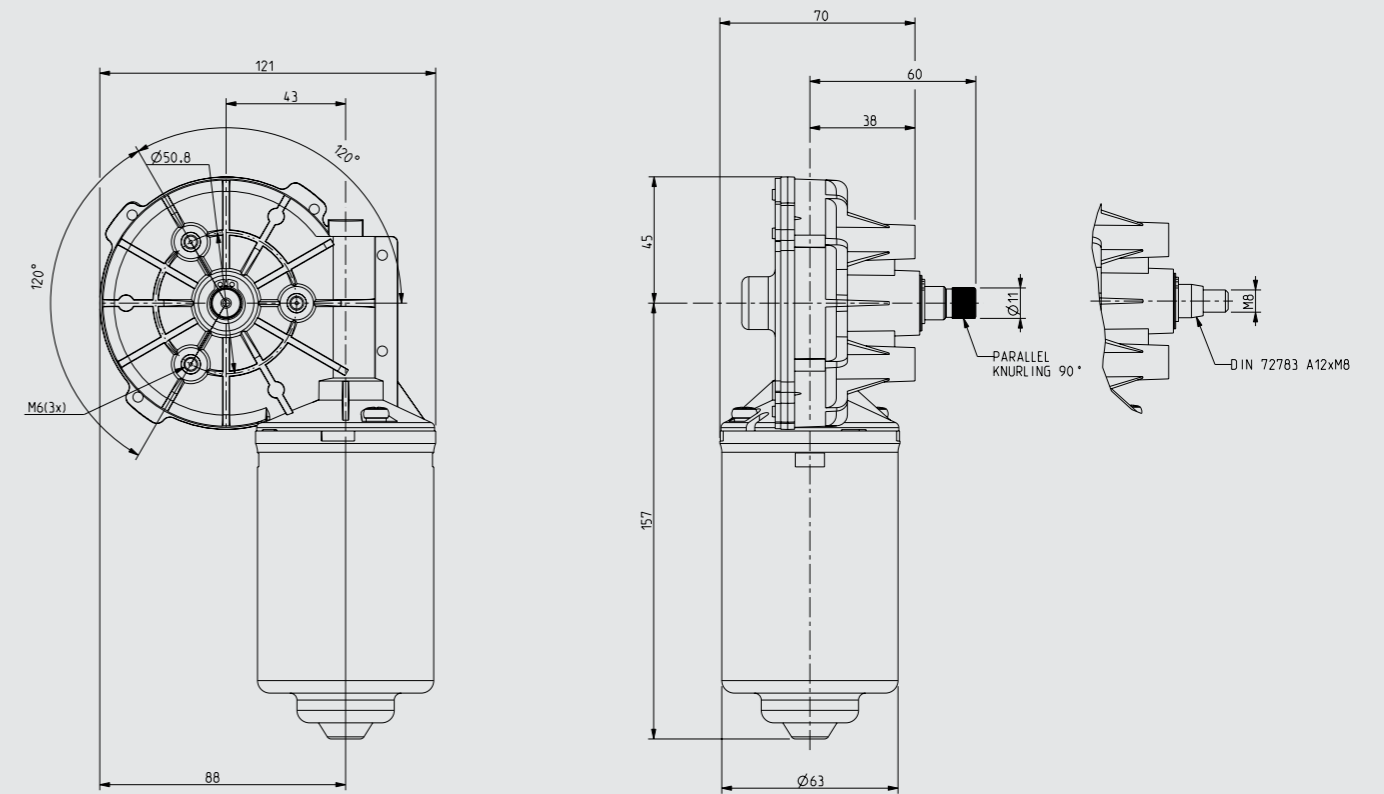
# MRT62-43 (Ø50,8)

Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2	1.5	2	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	40	40	45	45
Prima velocità (giri/min) First speed (rpm)	35		30	
Seconda velocità (giri/min) Second speed (rpm)			45	



MRT62-43 (Ø72)

MRT62-43 (Ø50,8)

# MRT76

Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	1.5	2.5	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	40	40	40	40
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			50	

# MRT76

Destro / Right

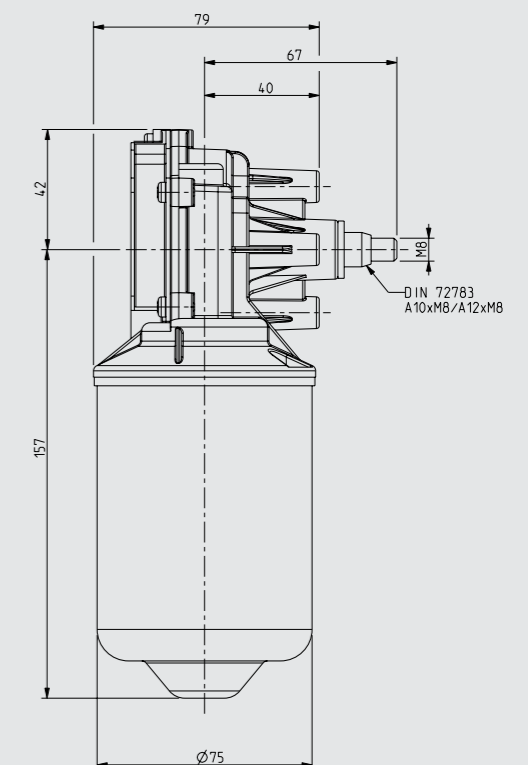
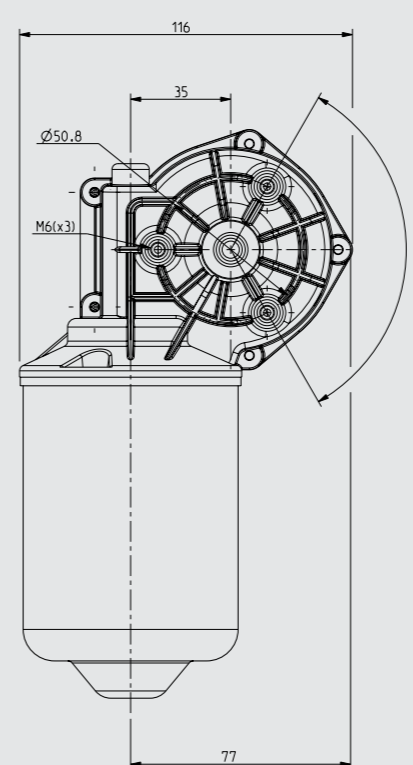
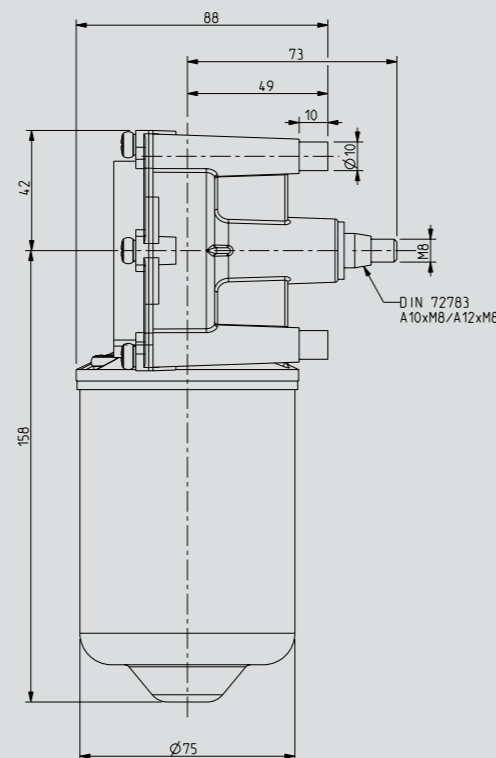
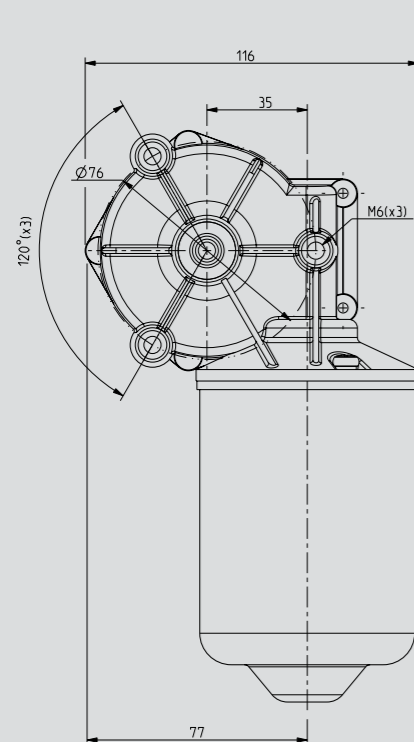


Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	1.5	2.5	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	40	40	40	40
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			50	

MRT76

MRT76





# MRT90-45

Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	3	2	3	2
Coppia nominale (Nm) Nominal torque	7	7	7	7
Coppia di spunto (Nm) Starting pair	55	65	55	65
Prima velocità (giri/min) First speed (rpm)	30		30	
Seconda velocità (giri/min) Second speed (rpm)			40	

# MRT90-45

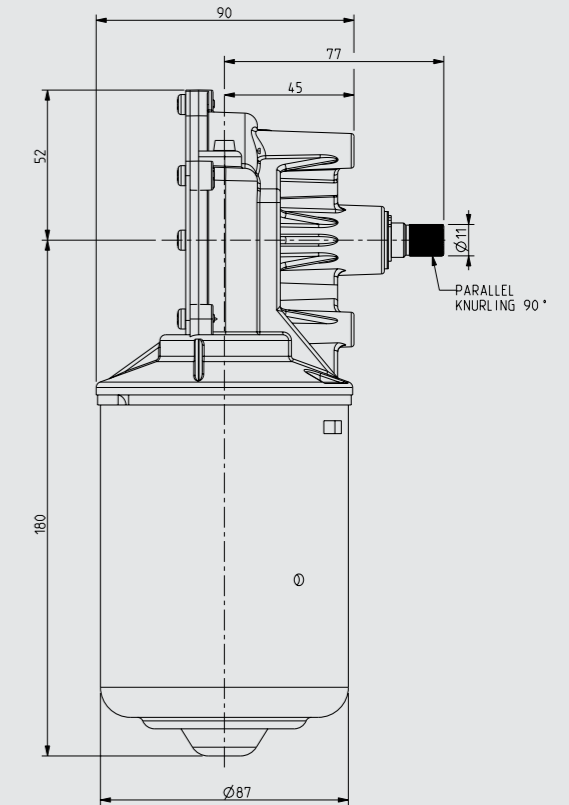
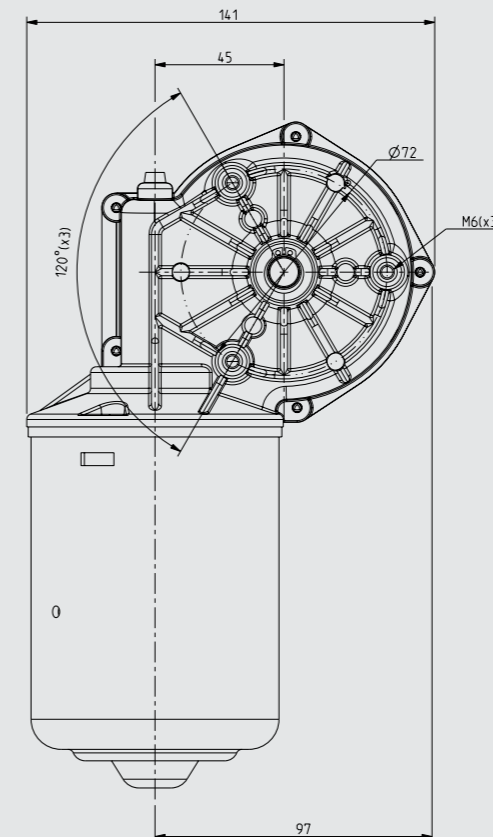
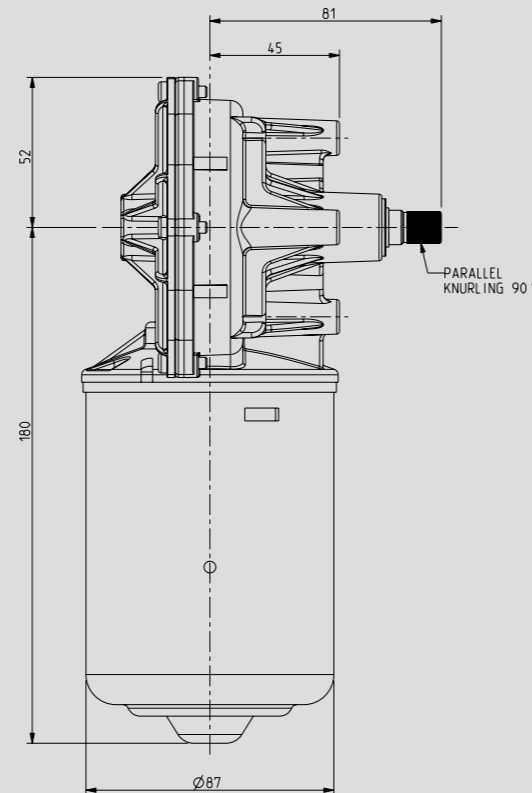
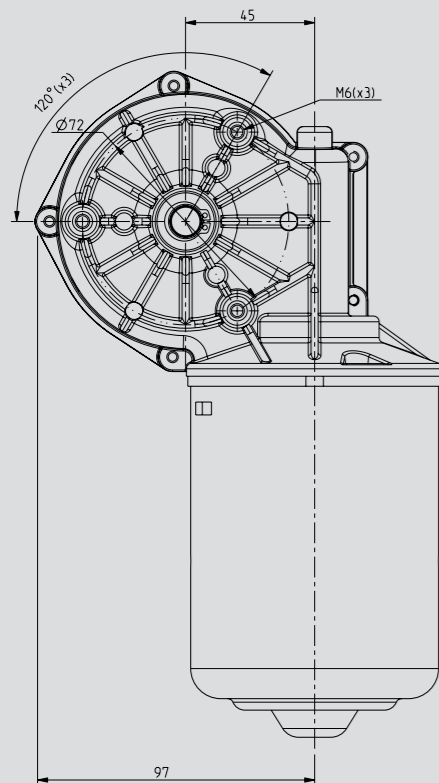
Destro / Right



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	3	2	3	2
Coppia nominale (Nm) Nominal torque	7	7	7	7
Coppia di spunto (Nm) Starting pair	55	65	55	65
Prima velocità (giri/min) First speed (rpm)	30		30	
Seconda velocità (giri/min) Second speed (rpm)			40	

MRT90-45



MRT90-45

# MRT90-56

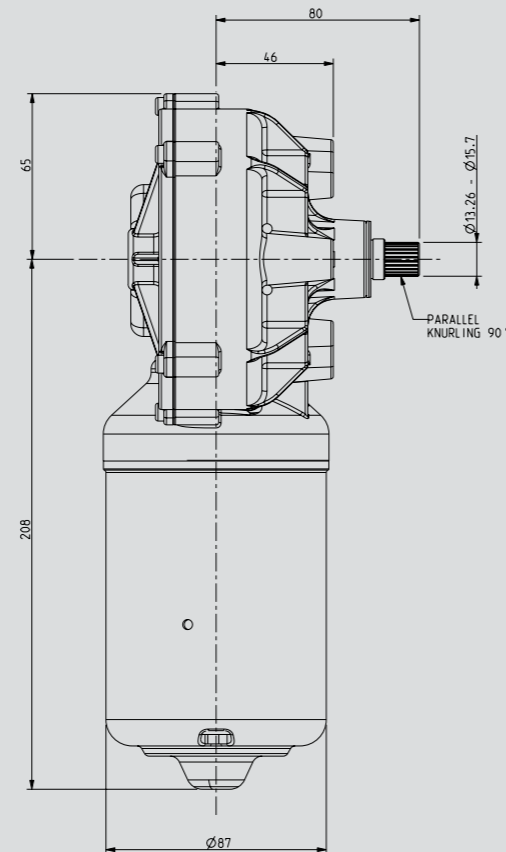
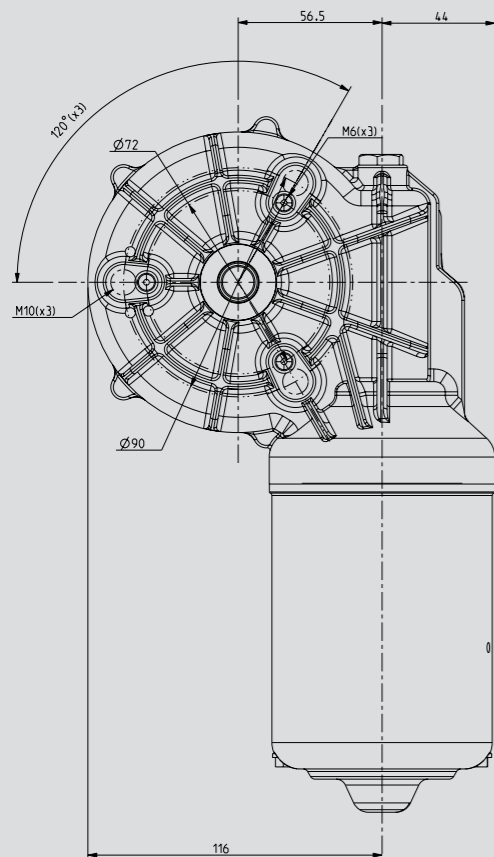
Sinistro / Left



Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	8	4	12	6
Coppia nominale (Nm) Nominal torque	7	10	6	7
Coppia di spunto (Nm) Starting pair	70	100	60	80
Prima velocità (giri/min) First speed (rpm)	27		27	
Seconda velocità (giri/min) Second speed (rpm)			35	

MRT90-56



# MRT62-TP1



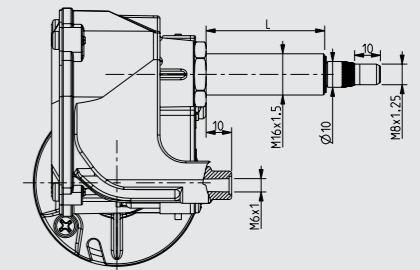
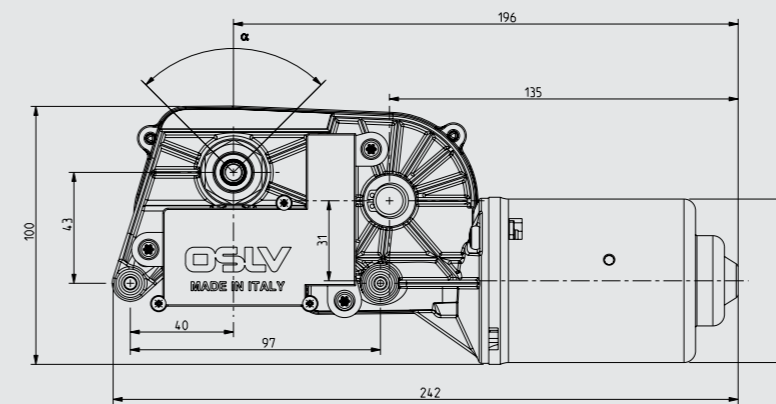
Dati tecnici / Technical Data

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	2.5	1.5	2.5	1.5
Coppia nominale (Nm) Nominal torque	4	4	4	4
Coppia di spunto (Nm) Starting pair	10	10	10	10
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)			50	

MRT62-TP1

Motoriduttore cinematismo interno (tipo uno)

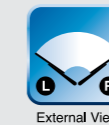
Wiper motor with internal mechanism



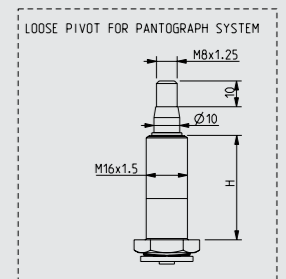
Dimensioni / Dimensions

L (mm)	20	30	35	40	50	65
H (mm)	29	35	50	55.5	60	70
α	80°	90°	105°	136°		

PARK POSITION



External View



# MRT62-CNT

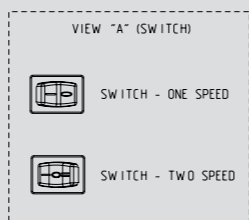
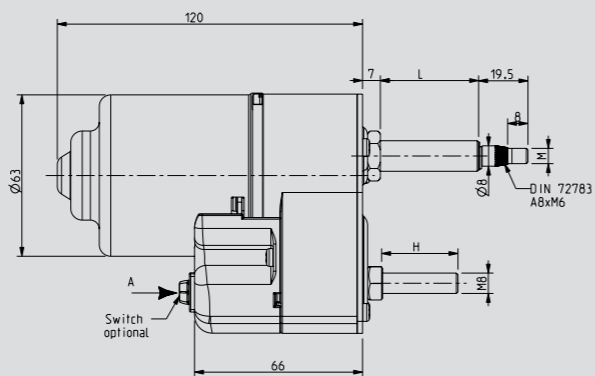
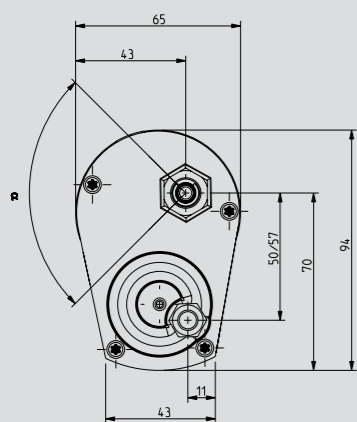


**Dati tecnici / Technical Data**

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed		2 Velocità 2 Speed	
	Tensione nominale (V) Nominal tension (V)	12	24	12
Tensione di prova (V) Trial tension	13.5	27	13.5	27
Corrente nominale (A) Nominal current	1.5	1	1.5	1
Coppia nominale (Nm) Nominal torque	1	1	1	1
Coppia di spunto (Nm) Starting pair	10	10	10	10
Prima velocità (giri/min) First speed (rpm)	35		35	
Seconda velocità (giri/min) Second speed (rpm)	-		50	

Motoriduttore cinematismo interno

Wiper motor with internal mechanism for arm and blade max 500 mm



**Dimensioni / Dimensions**

L (mm)	18	28	38	58
H (mm)	16	20	25	30



$\alpha$	80°	90°	110°
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# MRT50

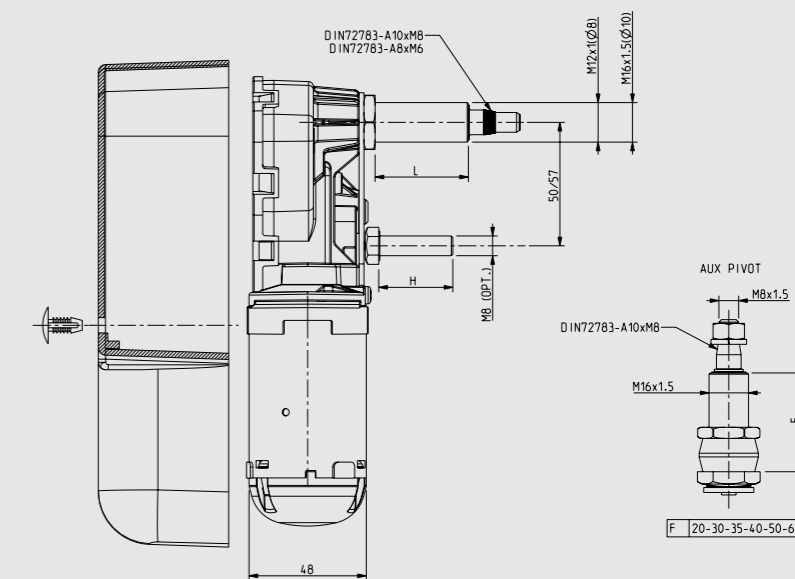
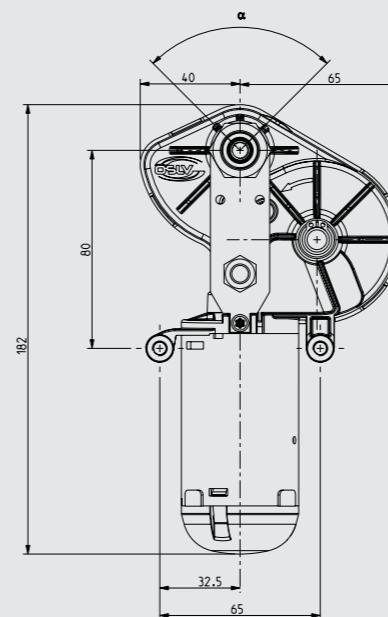


**Dati tecnici / Technical Data**

PRESTAZIONI PERFORMANCE	1 Velocità 1 Speed	
	Tensione nominale (V) Nominal tension (V)	12
Tensione di prova (V) Trial tension	13.5	27
Corrente nominale (A) Nominal current	-	-
Coppia nominale (Nm) Nominal torque	1	1
Coppia di spunto (Nm) Starting pair	10	10
Prima velocità (giri/min) First speed (rpm)	40	40
Seconda velocità (giri/min) Second speed (rpm)	-	-

Motoriduttore cinematismo interno

Wiper motor with internal mechanism for arm and blade max 500 mm



**Dimensioni / Dimensions**

L (mm)	25	35	40	60
H (mm)	16	20	30	60

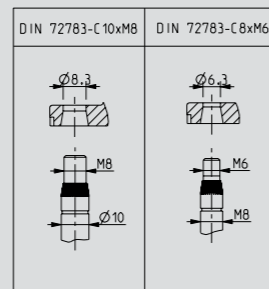
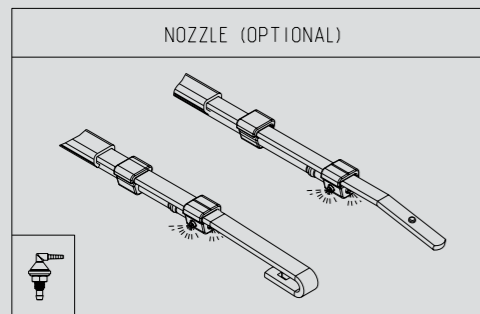
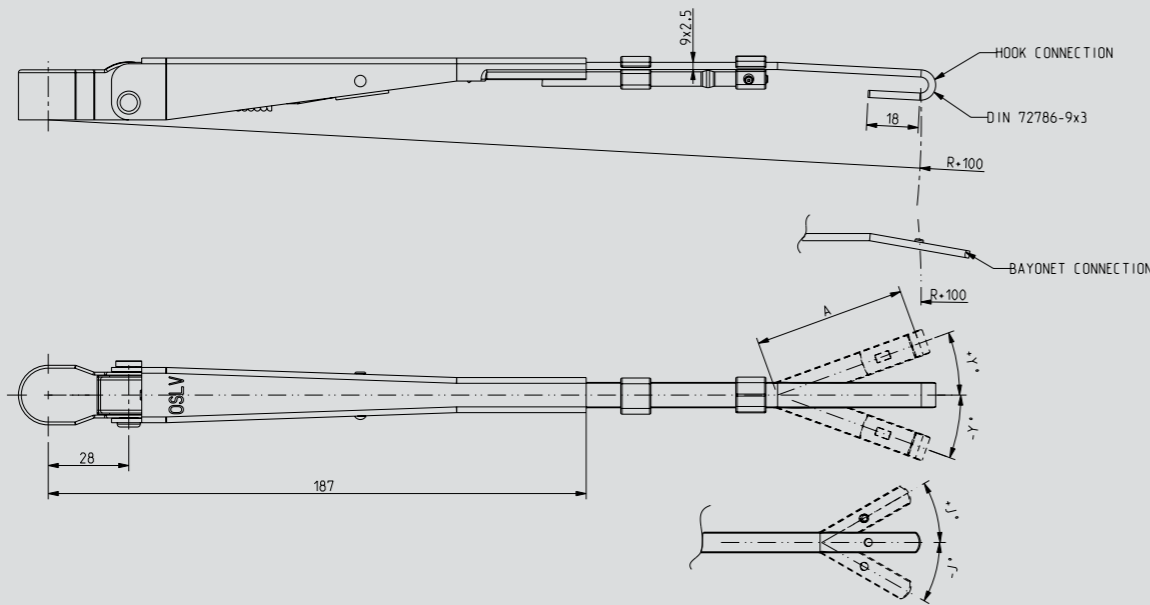


$\alpha$	50°	60°	70°	80°	90°	105°	120°	135°	145°	165°	175°
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# Adjustable single arm 9x2.5



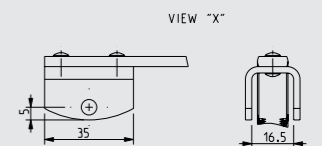
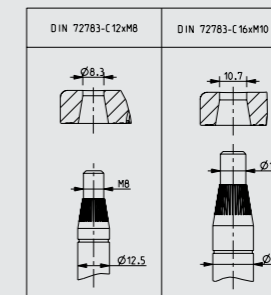
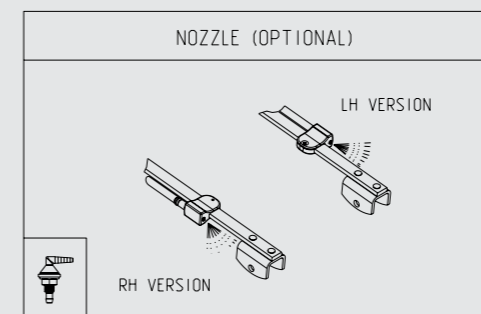
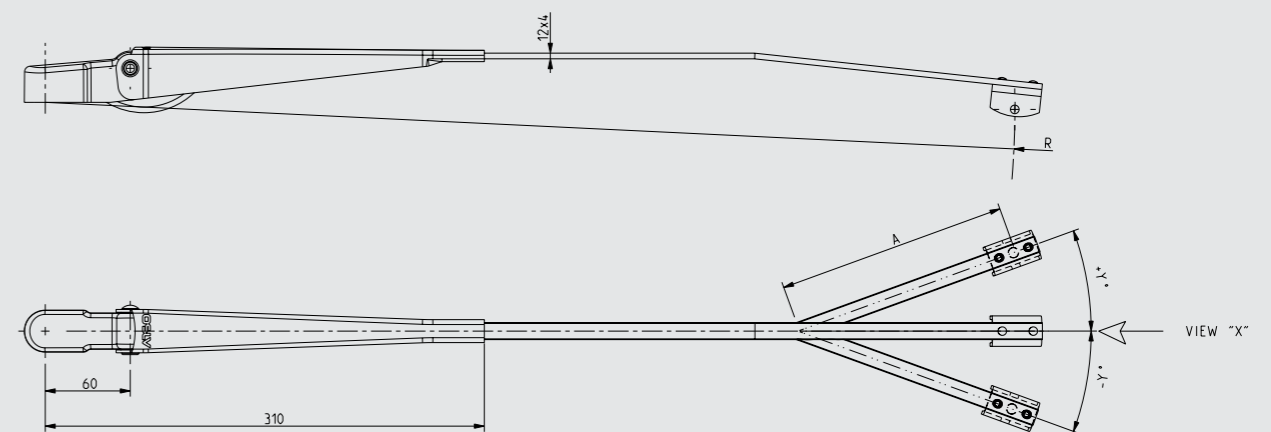
Dati tecnici / Technical Data							
R (mm)	300	315	330	350	400	450	500
Y (max)	± 20°						



# Single arm 9x3



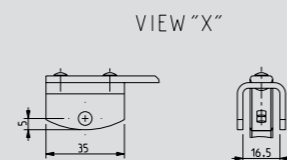
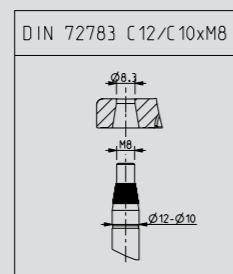
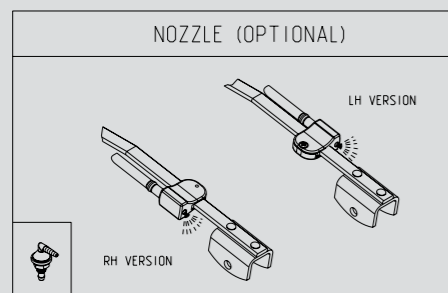
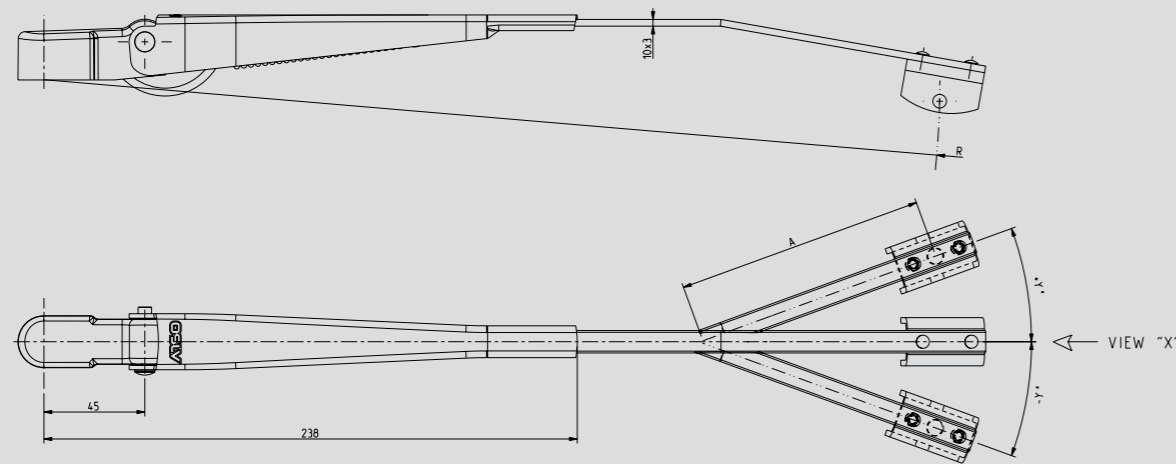
Dati tecnici / Technical Data							
R (mm)	275	300	350	400	450	500	
Y (max)	± 20°						



# Single arm 10x3



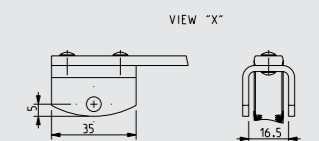
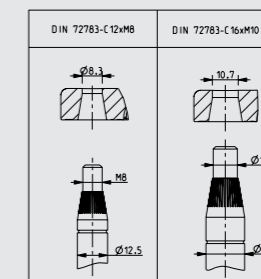
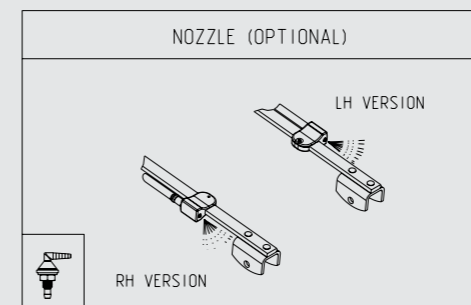
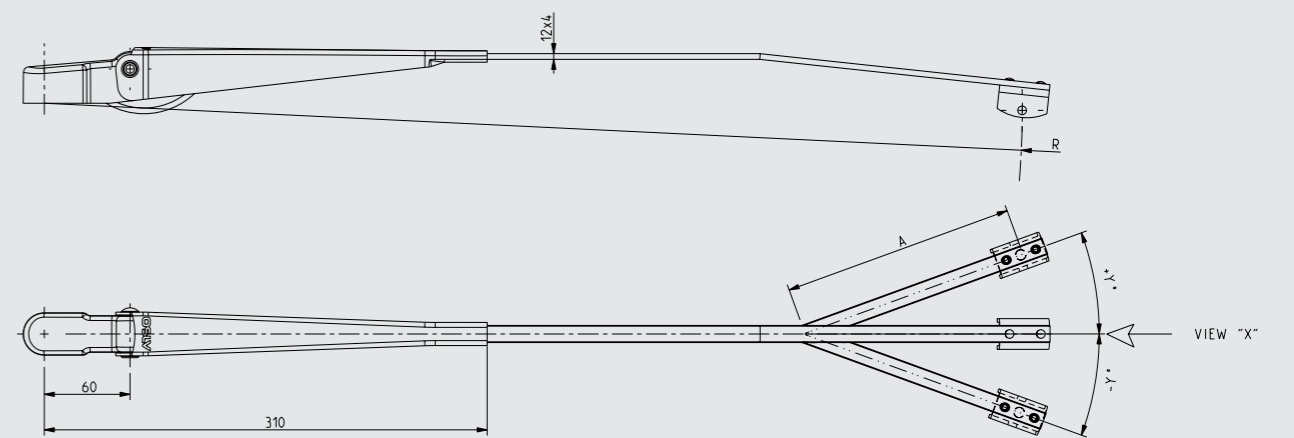
Dati tecnici / Technical Data							
R (mm)	450	500	550	600	650	700	
Y (max)	± 20°						



# Single arm 12x4



Dati tecnici / Technical Data							
R (mm)	275	300	350	400	450	500	
Y (max)	± 20°						



Single arm 10x3

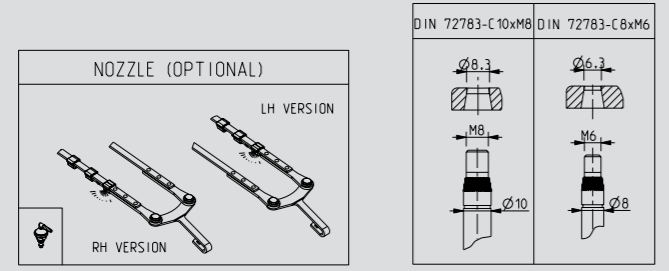
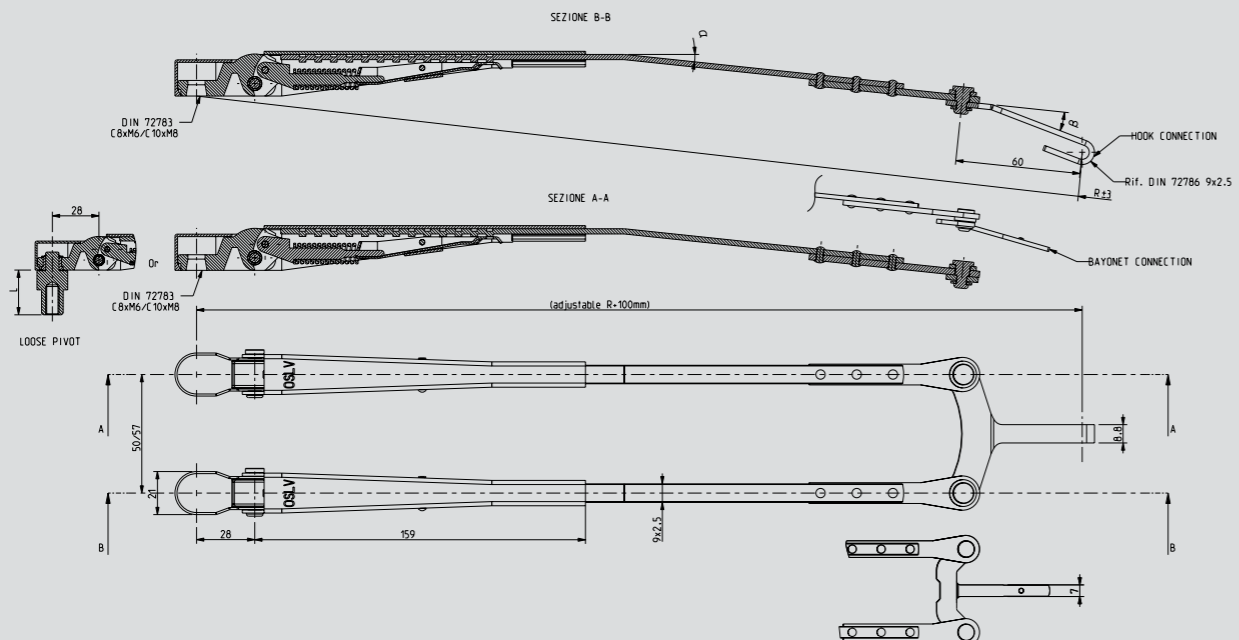
Single arm 12x4

# Adjustable pantograph arm 9x2.5



**Dati tecnici / Technical Data**

<b>R (mm)</b>	300	350	400	425	450	500	550
<b>L (mm)</b>	7	15	26,5	35	46		

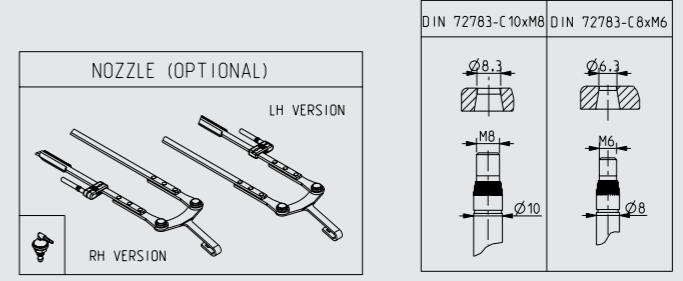
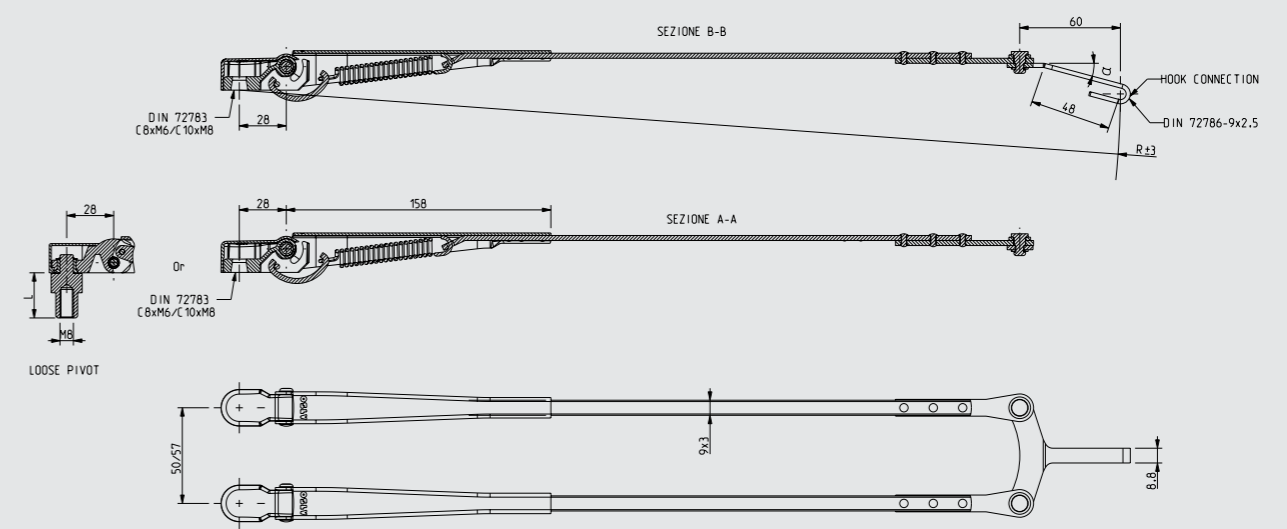


# Pantograph arm 9x3



**Dati tecnici / Technical Data**

<b>R (mm)</b>	400	450	500	550	600
<b>L (mm)</b>	7	15	26,5	35	46



Adjustable pantograph arm 9x2.5

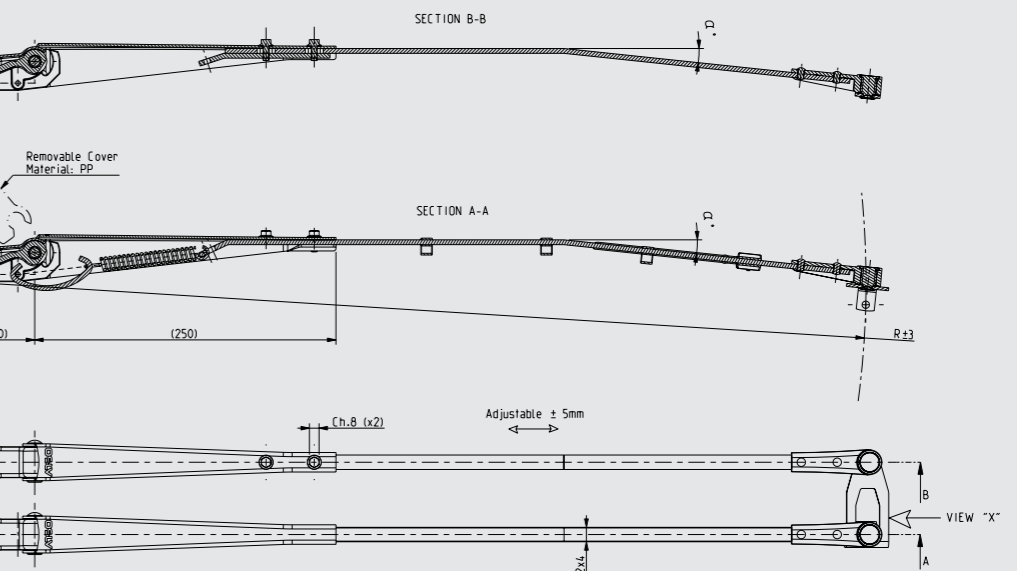
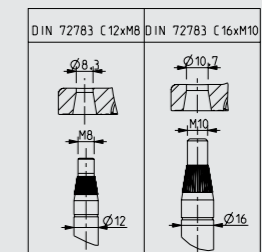
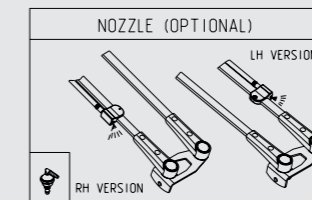
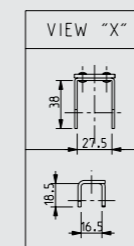
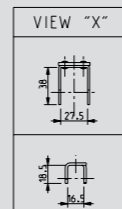
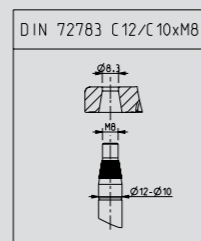
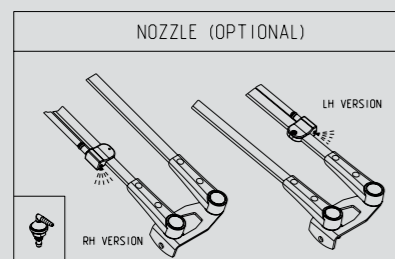
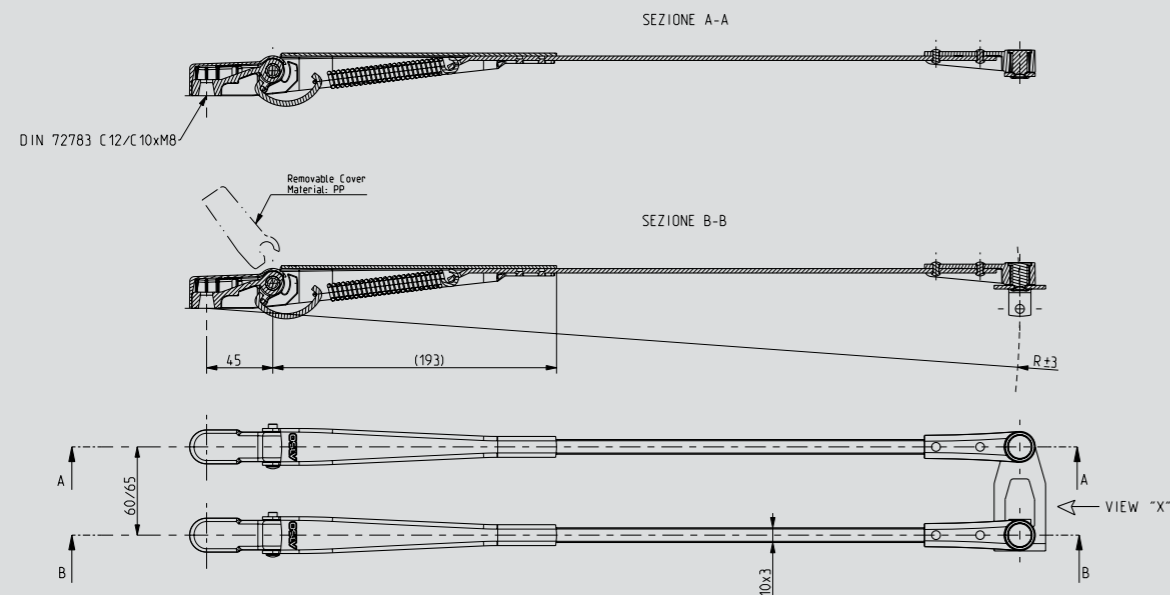
Pantograph arm 9x3

# Pantograph arm 10x3



Dati tecnici / Technical Data

R (mm)	450	500	550	600	650	700
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Dati tecnici / Technical Data

R (mm)	650	700	750	800	850	900	950	1000
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Pantograph arm 10x3

Pantograph arm 12x4

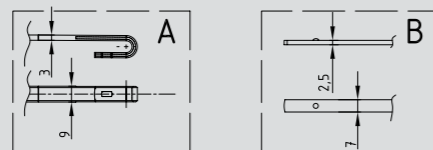
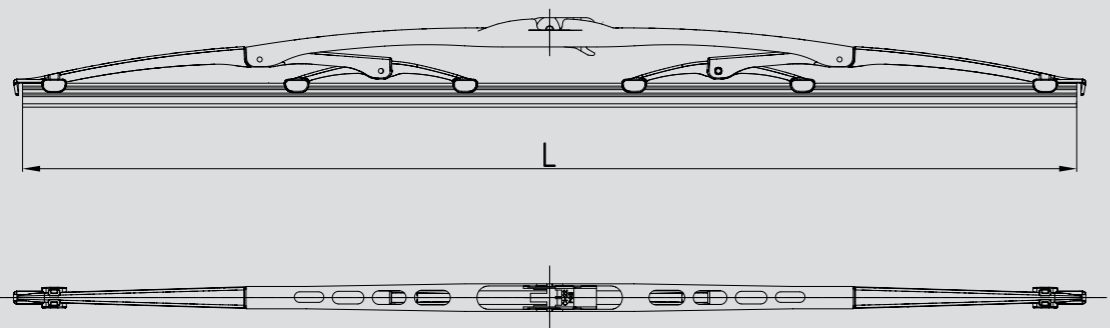
## Blades

Hook connection / bayonet closure



Dati tecnici / Technical Data

L (mm)	290	300	330	350	380	400	450	480	500	550	600
A	X	X	X	X	X	X	X	X	X	X	X
B	X	X	X	X	X	X	X	X	X	X	X



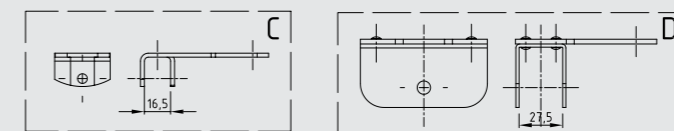
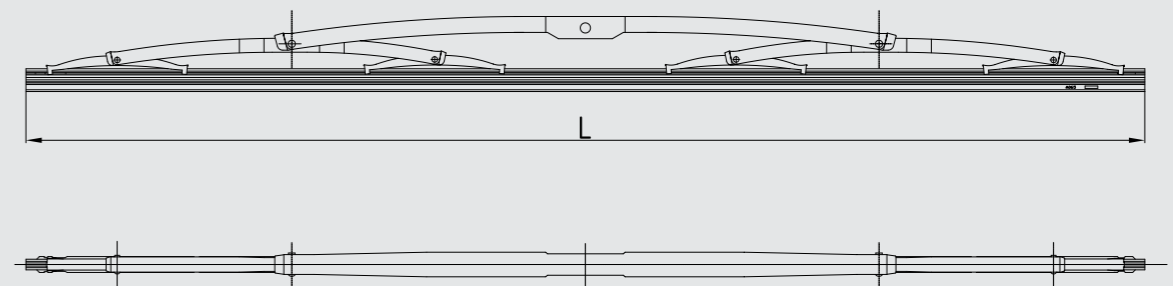
## Blades "Truck"

Bridge connection



Dati tecnici / Technical Data

L (mm)	600	650	700	800	900	1000	1200	1300
C	X	X	X	X	-	-	-	-
D	-	-	-	-	X	X	X	X





## OSLV RESEARCH & DEVELOPMENT

## RICERCA E SVILUPPO

OSLV testa i propri prodotti nelle condizioni più estreme, come quelle dei rally. Da vari anni è impegnata in questa difficile disciplina come main sponsor del pilota Alfredo De Dominicis nei campionati Mondiale, Italiano e Americano Rally.

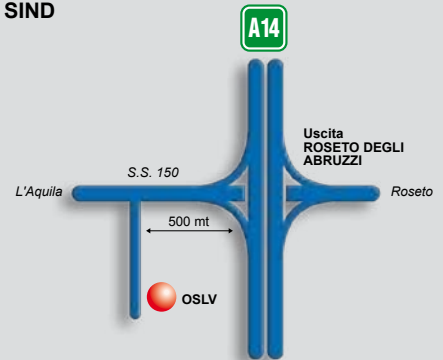
OSLV tests its products under extreme conditions as in the Rally. For many years the company has been involved in this difficult discipline as main sponsor of the pilot Alfredo De Dominicis in the championship in Italy, America and in the World.

*La société OSLV teste ses produits en conditions extrêmes comme les Rallys. Depuis beaucoup d'années, la société est engagée dans cette difficile discipline comme le principal sponsor du pilote Alfredo De Dominicis dans les championnats de Rally en Italy, Amérique et du monde.*

Die Fa. OSLV prüft Ihre Produkte unter extremsten Bedingungen, wie in den Rallys. Seit mehreren Jahren ist sie in dieser schwierigen Disziplin als Hauptsponsor des Pilotens Alfredo De Dominicis in den Rally-Meisterschaften Italien, Amerika und Welt tätig.

# Dove siamo

WHERE WE ARE - OU NOUS JOINDRE - WO WIR SIND



**Come raggiungerci:**  
IN AUTO  
A 500 mt dall'uscita A14 Roseto degli Abruzzi

IN TRENO  
Stazione Pescara - Roseto degli Abruzzi

IN AEREO  
Aeroporto di Pescara

**How to reach us:**  
BY CAR  
at 500 m from the highway A14 exit Roseto degli Abruzzi

BY TRAIN  
railway station Pescara-Roseto degli Abruzzi

BY AIRPLANE  
Airport Pescara

**Pour nous rejoindre:**  
PAR VOITURE  
à 500 m de la sortie de l'autoroute A14 Roseto degli Abruzzi

PAR TRAIN  
gare de Pescara - Roseto degli Abruzzi

PAR AVION  
aéroport de Pescara

**Wie Sie uns erreichen können:**  
MIT AUTO  
500 m von der Autobahnausfahrt der A14 Roseto degli Abruzzi

MIT DER BAHN  
Bahnhof Pescara - Roseto degli Abruzzi

MIT FLUGZEUG  
Flughafen Pescara

## Contatti

CONTACT • KONTAKT

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